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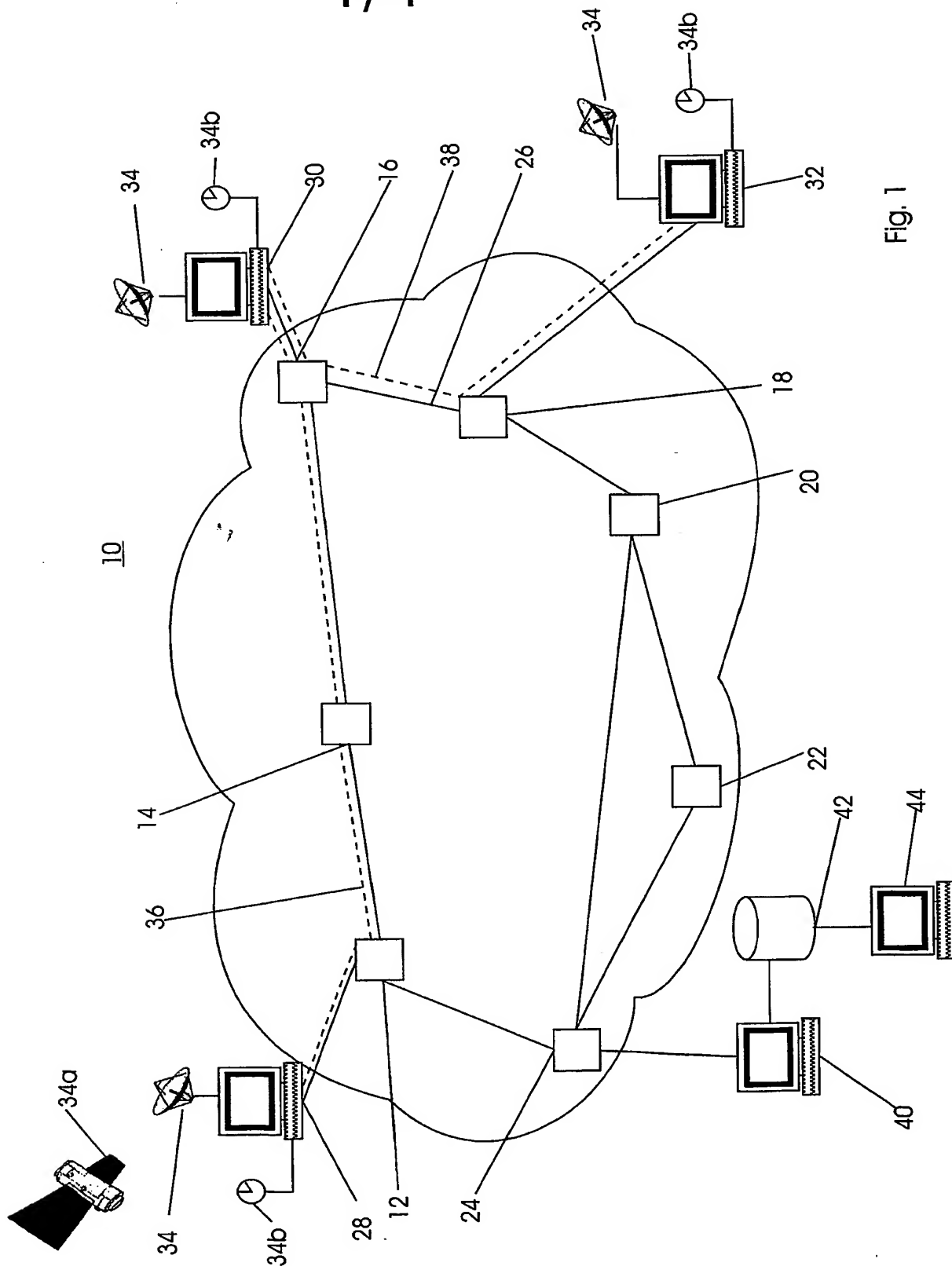


Fig. 1

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| | | | | | | | | | |
|--------------------------|---|---|---|---|---|---|---|---|---|
| Status matrix | | | | | | | | | |
| File Help | | | | | | | | | |
| Status display | 1 | 2 | 3 | 4 | 5 | 6 | 7 | 8 | 9 |
| 1 Measuring computer 28 | | | | | | | | | |
| 2 Measuring computer 30 | | | | | | | | | |
| 3 Measuring computer 32 | | | | | | | | | |
| 4 Measuring computer ... | | | | | | | | | |
| 5 Measuring computer ... | | | | | | | | | |
| 6 Measuring computer ... | | | | | | | | | |
| 7 Measuring computer ... | | | | | | | | | |
| 8 Measuring computer ... | | | | | | | | | |
| 9 Measuring computer ... | | | | | | | | | |

52

46

48



54

50

Fig. 2

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56

| Measuring computer 28 => Measuring computer 30 | | | | |  |  |
|--|----------|-----------|--------|--|---|---|
| | OWD (ms) | IPDV (ms) | PL (%) | | | |
| Best Effort | 2.6 | 0.3 | 0 | | | |
| TC 1 | 2.6 | 0.3 | 0 | | | |
| TC 2 | 2.3 | 0.3 | 6.25 | | | |
| Low Loss | 2.3 | 0.3 | 0 | | | |
| Best Effort | 2.3 | 0.3 | 0 | | | |
| TC 1 | 2.3 | 0.3 | 0 | | | |
| TC 2 | 2.6 | 0.3 | 0 | | | |
| Low Loss | 2.3 | 0.3 | 0 | | | |
| Best Effort | 2.3 | 0.3 | 6.25 | | | |

58

60

62

64

Fig. 3

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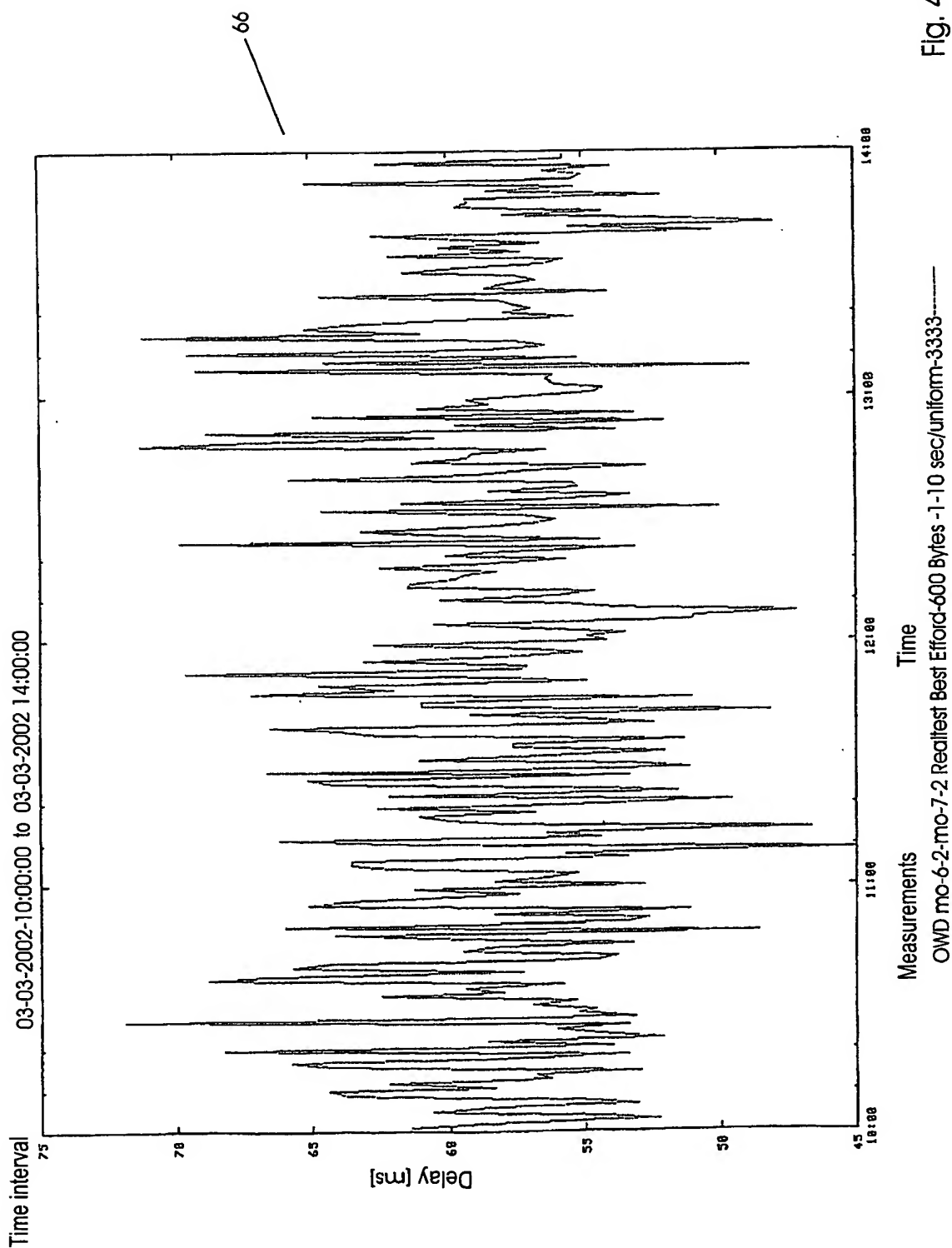


Fig. 4